# **INTRODUCTION**

- . Muscle fatty infiltration after tendon rupture is responsible for muscle atrophy, and consequently, muscle function loss.
- This problem is more usually in rotator cuff injuries [1]. The rotator cuff is the group of muscles and tendons that act to **stabilize the shoulder and allow for its extensive range of motion.**
- The passive and active behaviour of the Infraspinatus and Supraspinatus muscles of a mice model has been analyzed.

#### **METHODS**

#### **Experimental characterization Computational model**

### **RESULTS**

 $\bar{\Psi}_a = f_1\left(\bar{\lambda}_a\right)f_2\left(f_r,t\right)\bar{\Psi}'_a\left(\bar{J}_4\right)$  $\bar{\Psi}'_a = \frac{1}{2} P_0 \left( \bar{J}_4 - 1 \right)^2 \qquad \quad \bar{J}_4 = \bm{m}_0 \cdot \bar{\bm{C}}_e \bm{m}_0 = \bar{\lambda}_e$  $\mathbf{P}_a - \frac{\partial \bar{\Psi}}{\partial \bar{\lambda}_a} + \left(2 \bar{\mathbf{C}}_e \frac{\partial \bar{\Psi}}{\partial \bar{\mathbf{C}}_e} \bar{\mathbf{F}}_a^{-T}\right) : \frac{\partial \bar{\mathbf{F}}_a}{\partial \bar{\lambda}_a} = C \dot{\bar{\lambda}}_a \; .$ 

**CONCLUSIONS**





## **EXPERIMENTAL AND NUMERICAL CHARACTERIZATION OF THE ACTIVE BEHAVIOUR OF MOUSE ROTATOR CUFF MUSCLES**

#### P. Martins<sup>1,2</sup>, A. Pérez<sup>3,4</sup>, G. Abizanda<sup>3,4</sup>, B. Calvo<sup>1,5</sup>, J. Grasa<sup>1,5</sup>

Objective: This work establishes a new framework based on an animal model and computational simulation to understand the **biomechanics of the joint and to test new treatments**

**The results show the difference in the mechanical properties of both infra and supraspinatus muscles.**

**The passive behavior shows a stiffer supraspinatus compared with the infraspinatus.**

**The maximum force of both muscles and the contractile properties according to time has also been determined. The data and fittings h-ave been used to develop the FEM simulations of the rotator cuff muscles and will be used to investigate the biomechanics and damage effects.**

**Passive Behaviour**



The experimental study was conducted in accordance with the provisions of the European and Spanish legal The geometry of bone and muscles was obtained from MRI image segmentation. normatives (RD53/2013). Isolated supraspinatus (n=3) and infraspinatus (n=3) mouse (wild-type (WT, C57BL/6J)) muscles were prepared to measure their maximum active isometric force and tested afterwards uniaxially till fracture.

- [1] Shirasawa, H., Matsumura, N., Shimoda, M. et al. Inhibition of PDGFR signaling prevents muscular fatty infiltration after rotator cuff tear in mice. Sci Rep 7, 41552 (2017).
- [2] Calvo B, Ramírez A, Alonso A, Grasa J, Soteras F, Osta R, Muñoz MJ. Passive nonlinear elastic behaviour of skeletal muscle: experimental results and model formulation. J Biomech. 43(2):318-25 (2010).
- [3] Hernández-Gascón, B., Grasa, J., Calvo, B., Rodríguez, J. F. A 3D electro-mechanical continuum model for simulating skeletal muscle contraction. J. Theor. Biol. 335, 108–118 (2013).
- *1 Aragón Institute of Engineering Research (i3A), University of Zaragoza, Spain*
- *2 Fundación Aragonesa para la investigación y desarrollo (ARAID)*
- *3 Regenerative Medicine Program, Foundation for Applied Medical Research (FIMA), University of Navarra (UNAV)*
- *4 Instituto de Investigación Sanitaria de Navarra (IdiSNA)*
- *5 Bioengineering, Biomaterials and Nanomedicine Networking Biomedical Research Centre (CIBER-BBN), Zaragoza, Spain*



**Passive response parameters Infraspinatus Supraspinatus**  $C_1$  (MPa) 0.001047 0.001465  $C_3$  (MPa)  $\begin{array}{|c|c|c|c|c|c|} \hline \text{0.001440} & \text{0.001533} \ \hline \end{array}$  $c_{4}$ 0.453006 0.634963  $C_5$  (MPa) 0.026128 0.031050  $\begin{array}{|c|c|c|c|c|}\n\hline\nC_6 & (MPa) & -0.037105 & -0.04104 \\
\hline\n\end{array}$  $c_7$ -0.023900 -0.02941  $\bar{I}_{40}$ 1.464100 1.322500  $\bar{I}_{4_{\rm ref}}$ 2.656900 2.250000



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#### **Mathematical formulation**

**Active Behaviour** 



The active and passive behavior of the muscle tissue is modelled within the continuum mechanics framework. The tissue is considered as an hyperelastic transversely isotropic material. The strain energy function is decoupled into a volume-changing and a volume-preserving parts in order to handle the quasiincompressibility constraint:

To handle the anisotropy of the material, the **muscle fibers** directions have to be incorporated into the model. These orientations were obtained using the software Comsol Multiphysics v. 5.3.



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 $\bar{\Psi}_p = c_1 \left( \bar{I}_1 - 3 \right) + \bar{\Psi}_{pf} \; ,$ 

 $\bar{\Psi}_{pf} = \left\{ \begin{array}{ll} 0 & \bar{I}_4 < \bar{I}_{40} \ \frac{c_3}{c_4}\left(\exp^{c_4\left(\bar{I}_4 - \bar{I}_{40}\right)} - c_4\left(\bar{I}_4 - \bar{I}_{40}\right) - 1\right) & \bar{I}_4 > \bar{I}_{40} \quad \text{and} \quad \bar{I}_4 < \bar{I}_{4_\text{ref}} \ \bar{C}_5\sqrt{\bar{I}_4} + \frac{1}{2}c_6\ln\left(\bar{I}_4\right) + c_7 & \bar{I}_4 > \bar{I}_{4_\text{ref}} \end{array} \right.$ 

Experimental force versus stretch relationships for both Infraspinatus and Supraspinatus muscles were analyzed to characterize the passive behaviour of the tissue. The parameters of the model fitting were obtained using the Levenberg-Marquardt optimization algorithm.



The active response of the Infraspinatus muscle was characterized under isometric

contractions of 0.5 s. The tissue was stimulated with electrical pulses of 10 ms and 100 V at 100 Hz.

**Total displacement field (mm)** obtained during the contraction of the muscle

Time=0.6 s Surface: First principal stress (MPa)

**Active fiber stretch** represented along the fiber directions used by the model discretization











Evolution of **muscle force** (mN) during the contraction together with the computational outcome

> **First principal stress** (MPa) distribution along the tissue at the contraction peak.

 $z \rightarrow x$ 



#### **Computational Results**













Experimental uniaxial passive tests of both muscles and numerical fitting

